

# **BME I5000: Biomedical Imaging**

### Lecture 9 Magnetic Resonance Imaging (imaging)

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# Schedul

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- 1. Introduction, Spatial Resolution, Intensity Resolution, Noise
- 2. X-Ray Imaging, Mammography, Angiography, Fluoroscopy
- 3. Intensity manipulations: Contrast Enhancement, Histogram Equalisation
- 4. Computed Tomography
- 5. Image Reconstruction, Radon & Fourier Transform, Filtered Back Projection
- 6. Nuclear Imaging, PET and SPECT
- 7. Maximum Likelihood Reconstruction
- 8. Magnetic Resonance Imaging
- 9. Fourier reconstruction, k-space, frequency and phase encoding
- 10. Optical imaging, Fluorescence, Microscopy, Confocal Imaging
- 11. Enhancement: Point Spread Function, Filtering, Sharpening, Wiener filter
- 12. Segmentation: Thresholding, Matched filter, Morphological operations
- 13. Pattern Recognition: Feature extraction, PCA, Wavelets
- 14. Pattern Recognition: Bayesian Inference, Linear classification

### MRI – How to generate images using NMR

Nuclear spins resonate at a frequency proportional to the external magnetic field

$$\omega = \gamma B_0$$

**Basic idea of MRI**: Change the  $B_0$  field with space and the resonance frequency will change with space.

$$\omega(x) = \gamma B_0(x)$$

The detected resonance signal (FID) contains multiple frequency components each giving information about a different portion of space!

City College of New York



### MRI – How to generate images using NMR





# MRI – Signal detected in MRI

Recall that the signal due to the bulk magnetization precessing at  $\omega$  detected in the *x* and *y* coils can be written as:

$$s(t) = s_x(t) + i s_y(t) \propto M_{xy}(0) e^{-t/T_2^*} e^{-i\omega t}$$

Signal intensity scales with  $M_{xy}(0)$  - the magnitude of the transverse magnetization at the end of the RF pulse.  $M_{xy}(0)$  is proportional to the number of resonating spins in the material, or the proton density  $\rho(r)$ . It is dependent on the tissue and therefore dependent on space r.

#### **MRI** generates images of $\rho(r)$ !

 $M_{xy}(0)$  also depends on the specifics of the pulse sequence. By manipulating the pulse sequence MRI can generate images of  $\rho(\mathbf{r})$  that are modulated by physical properties that affect  $T_1$  or  $T_2$ .



# **MRI – Signal detected in MRI**

The main idea is to apply a  $B_0$  field with a magnitude that also depends on space, so that the frequency of the resonance signal relates to space,  $\omega(\mathbf{r}) = \gamma B_0(\mathbf{r})$ :

$$s(t) \propto e^{-t/T_2^*} \rho(\mathbf{r}) e^{-i\gamma B_0(\mathbf{r})t}$$

(where we have ignored the effect of  $T_1$  and  $T_2$ ). The signal emitted by the entire body is then the sum over space:

$$s(t) \propto e^{-t/T_2^*} \int_{body} d\mathbf{r} \rho(\mathbf{r}) e^{-i\gamma B_0(\mathbf{r})t}$$

Note that  $B_0(r)$  is parallel to the *z*-axis, only its magnitude may now depend on the location in space *r*.



# MRI – Signal detected in MRI

For reconstruction it will be useful to define new signal that is 'demodulated' and without the  $T_2^*$  decay:

$$S(t) = s(t)e^{t/T_2^*}e^{i\omega_0 t}$$

Define also  $\Delta B_{z}(\mathbf{r})$  as the difference of  $B_{0}(\mathbf{r})$  over main  $B_{0}$ :

$$\Delta B_z(\mathbf{r}) = B_0(\mathbf{r}) - \omega_0 / \gamma$$

With this the MRI imaging equations becomes

$$S(t) = \int_{body} d\mathbf{r} \rho(\mathbf{r}) e^{-i\gamma \Delta B(\mathbf{r})t}$$



# MRI – $B_0$ gradient, frequency encoding

Lets assume we need spatial resolution in only one direction. For instance *x*. So we want to recover (ignoring *z* direction for now):

$$g(x) = \int dy \rho(x, y)$$

To do so, we apply a contribution  $B_0$  that changes linearly with x. The strengths of these 'x-gradient' is given by the constants  $G_x$ .





# MRI – $B_0$ gradient, frequency encoding

The imaging equation is now

$$S(t) = \int dx g(x) e^{-i\gamma G_x x t}$$

To put this in a more familiar notation lets define a new variable

$$k_x = \gamma G_x t$$
  $\gamma = \gamma / 2 \pi$ 

$$S(k_x) = \int dx g(x) e^{-i2\pi k_x x}$$

Evidently the detected signal S(k) is a Fourier transform of g(x), and we can recover it with the inverse Fourier transform.

$$g(x) = \int dx S(k_x) e^{i 2\pi k_x x}$$

This methods is therefore called *frequency encoding*. Obviously we can also apply a  $G_{y}$  gradient and obtain g(y).



### **MRI – Axial Reconstruction**

Notice that g(x) is the sum of  $\rho(x,y)$  along direction y, i.e. the direction orthogonal to the gradient  $G_x$ .



The signal  $S(k_x)$  detected in MRI during a  $G_x$  gradient is the Fourier transform of g(x).



#### **MRI – Axial Reconstruction**

Obviously one can make the gradient  $G_{\phi}$  have any orientation  $\phi$ , and measure the corresponding signal  $S(k,\phi)$ 



The signal  $S(k,\phi)$  detected in MRI during a  $G_{\phi}$  gradient is the Fourier transform of the Radon transform  $g(r,\phi)$ . If we record the signal repeatedly at different orientation  $\phi$  we can therefore apply the same Radon reconstruction as in CAT!



# **MRI – Axial Reconstruction**

By combining *x*, *y* gradients linearly we can get gradients that at an arbitrary orientation  $\phi$ :

$$\Delta B_{z}(\mathbf{r}) = G_{x}x + G_{y}y = G_{\phi} \cdot \mathbf{r}$$
$$G_{\phi} = \begin{bmatrix} G_{x} \\ G_{y} \end{bmatrix} = G_{\phi} \begin{bmatrix} \cos \phi \\ \sin \phi \end{bmatrix} \qquad \mathbf{r} = \begin{bmatrix} x \\ y \end{bmatrix}$$

The signal we obtain is then a Fourier transform of  $\rho(\mathbf{r})$  along that direction (the orthogonal directions are summed).

$$k_{\phi} = \begin{bmatrix} k_{x} \\ k_{y} \end{bmatrix} = k \begin{bmatrix} \cos \phi \\ \sin \phi \end{bmatrix} \qquad S(t, \phi) = \int dr \rho(r) e^{-i\gamma G_{\phi} \cdot rt} \\ k_{\phi} = \Im G_{\phi} t \qquad k_{\phi} = \Im G_{\phi} t \\ S(k, \phi) = \int dr \rho(r) e^{-i2\pi k_{\phi} \cdot r}$$



# **MRI – Gradient Echo Sequence**

90° and a  $G_x$  gradient will also generate a echo sequence. Spins at some locations spin faster than at others due to Gx. After sign reversal of  $G_x$  the faster spins become the slower ones, and vice versa. The time it takes the spins to catch up (re-phase) is called echo time  $(T_E)$  90°





# **MRI – Gradient Echo Sequence**

We can obtain different angles with different combinations of  $G_{r}$  and



The same can be done with at FID or Echo pulse sequence.



# **MRI – Gradient Echo Sequence**

For this pulse sequence the signal we detect is given by

$$S(t,\phi) = \int dr \rho(r) e^{-i\gamma G_{\phi} \cdot r(t-T_{E})}$$
$$k_{\phi} = \gamma G_{\phi}(t-T_{E})$$
$$S(k,\phi) = \int dr \rho(r) e^{-i2\pi k_{\phi} \cdot r}$$

or in Cartesian coordinates:

$$S(k_x, k_y) = \int dx dy \rho(x, y) e^{-i2\pi(k_x x + k_y y)}$$

i.e.  $S(k_x, k_y)$  is the 2D Fourier transform of  $\rho(x, y)$ .



#### MRI – k-space

Lets consider the RF signal we measure. It represents the data in the frequency domain, i.e. the "k-space".



Time starts at *t*=0 and is sampled in discrete points  $t = \Delta t n$ 



### MRI – k-space

Signals taken at multiple angles  $\phi$  cover the k-space and allow therefore reconstruction (left).



Is there a pulse sequence that can sample the Fourier space evenly as shown on the right so that we can use direct 2D Fourier inverse?



#### **MRI – Phase Encoding**

If spins precess at different speeds (due to a variable encoding gradient  $G_y$ ) during a fixed amount of time  $T_{pe}$  they will gain a different phase:





#### **MRI – Phase Encoding**

A phase encoding echo pulse sequence, which will sample the k-space along the  $k_x$  axis for different values of  $k_y$  is as follows:





### **MRI – Phase Encoding**

With a phase encoding gradient  $G_y$  in y direction and frequency encoding gradient in  $G_x$  in x direction the echo signal would be (ignoring the z direction again):

$$S(t,T_{pe}) = \int dx \, dy \rho(x,y) e^{-i\gamma G_x x(t-T_E) + \gamma G_y y T_{pe}}$$

which can be rewritten as a 2D Fourier transform with the following definitions:

$$k_{x} = \Im G_{\%x}(t - T_{E}) \qquad k_{y} = \Im G_{\%y} T_{pe}$$
$$S(k_{x}, k_{y}) = \int dx dy \rho(x, y) e^{-i2\pi(k_{x}x + k_{y}y)}$$



# **MRI – Slice selection**

So far we considered gradients applied *after* the RF pulse during free precession. A gradient  $G_z$  during the RF pulse will select a transversal slice that satisfies the *resonance condition*: The RF pulse affects the spin precession coherently only if the frequency matches the  $B_z$  field. For the rest  $M_{xy} = 0$  after  $\alpha$  pulse.



Only this slice will generate a signal!



### **MRI – Slice selection**

Note that a "hard" RF pulse contains high frequency components. It is therefore less selective in space as a "soft" pulse (sinusoid modulated by a sync functions -  $sin(\omega_0 t)$ \*sinc( $\omega t$ ):





#### MRI – a pulse sequence example

Example for a full pulse sequence with gradient echo and the corresponding path in k-space:





#### MRI – a pulse sequence example



Echos – refocussing of signal

Spin echo:

use a 180 degree pulse to "mirror image" the spins in the transverse plane

when "fast" regions get ahead in phase, make them go to the back and catch up

measure T2

ideally TE = average T2

Gradient echo:

flip the gradient from negative to positive

make "fast" regions become "slow" and vice-versa

measure T2\*

ideally TE ~ average T2\*



# **MRI – Summary for Magnetic fields**



High, constant, Uniform Field, B<sub>0</sub>.

Gradient Coils

Produce pulsed, linear gradients in this field.

$$G_x, G_y, \& G_z$$

RF coils

Transmit: B1 Excites NMR signal (FID). Receive: Senses FID.





# **MRI – Contrast properties**

The strength of the NMR signal produced by precessing protons in a tissue depends on T1, T2 of the tissue. The density of protons in the tissue. Motion of the protons (flow or

diffusion).

The MRI pulse sequence used

In a T1 "weighted" image the pulse sequence is chosen so that T1 has a larger effect than T2.

Images can also be made to be T1, T2 proton density or flow/diffusion weighted.



Source: Mark Cohen





# MRI – Contrast, T1, T2

- MRI Contrast is created since different tissues have different T1 and T2.
- Gray Matter: (ms) T1= 810, T2= 101
- White Matter: (ms) T1= 680, T2=92

Bone and air are invisible.Fat and marrow are bright.CSF and muscle are dark.Blood vessels are bright.Gray matter is darker than white matter.





# **Functional MRI**

fMRI measures blood oxigen level difference (BOLD). Measured full volume in about 2s. It is a T2\* weighted images. T2\* is fast, and dominated by inhomogeneity susceptibility-induced field distortions. Oxigenated blood has higher magnetic susceptibility. In 1990 Ogawa observes BOLD effect with T2\*: blood vessels became more visible as blood oxygen decreased. First fMRI image obtained in 1992.











# **Diffution Tensor Imaging**

Measures the diffusion of water molecules (m/s). Has orientation.

**Mechanism:** During the RF pulse a gradient is applied. This introduces a phase shift that depends on gradient direction. The same is repeated with opposite sign of the gradient, so that the phase shift is removed again, but not for spins (mostly water) which moved. Those spin will not align and the signal will be weaker. So if we take two images and subtract, we get a drop of signal strength where there was more diffusion. This is repeated with pulse gradients in different orientations to measure diffusion in different orientations.

DTI raw data. Color indicates oriantati on of diffusion



Fiber track tracing. Color indicates identity of the fiber track.





# **MR Spectroscopy Imaging**

MRS, also known as Chemical Shift Imaging, activates the tissue with a somewhat broader band RF pulse (multiple frequencies). Different molecules have slightly different resulting Bz field due to neighboring spins, so they will resonate at slightly different frequencies, typically only parts per million (ppm) of the hydrogen frequency. The detected RF signal has then a spectrum with peaks at resonant frequencies of different molecules.





# **MR Angiography**

MRA in a rat



#### Rapid MRA time resolved

