

### **BME I5100: Biomedical Signal Processing**

#### **Linear Discrimination**



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#### **Schedule**

#### **Week 1: Introduction**

Linear, stationary, normal - the stuff biology is **not** made of.

#### Week 1-4: Linear systems

Impulse response
Moving Average and Auto Regressive filters
Convolution
Discrete Fourier transform and z-transform
Sampling

#### Week 5-8: Random variables and stochastic processes

Random variables Moments and Cumulants Multivariate distributions Stochastic processes

#### Week 9-14: Examples of biomedical signal processing

Probabilistic estimation

Harmonic analysis - **estimation** circadian rhythm and speech

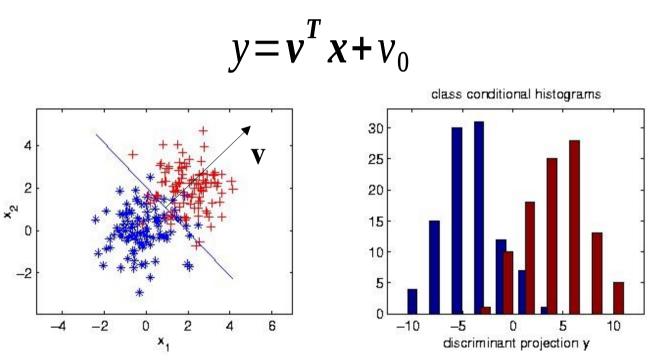
Linear discrimination - **detection** of evoked responses in EEG/MEG

Independent components analysis - **analysis** of MEG signals Dynamical Models - Kalman filter and Hidden Markov Models Matched and Wiener filter - **filtering** in ultrasound



#### **Linear Discrimination**

Given samples x from two classes  $c_1$  and  $c_2$  find vector  $\mathbf{v}$  so that the projection y separates the two classes:



Redefine  $\mathbf{x} = [1, x_1, x_2, ..., x_d]^T$  and  $\mathbf{v} = [v_0, v_1, v_2, ..., v_d]^T$  to write in short:

$$y = \mathbf{v}^T \mathbf{x}$$



The goal is to find a mapping from *x* to class label *c* or at least an expected value:

$$\hat{c} = f(y) = f(\mathbf{v}^T \mathbf{x})$$

However, since there is overlap, rather than making a fixed determination on the class label we will build a model that tells us what is the likelihood of a class *c* given input *x*.

$$p(c|y) = p(c|\mathbf{v}^T \mathbf{x})$$

We will now derive an expression of the Likelihood of class labels *c* given projection *y*, which are given by input *x* and parameters *v*. The optimal *v* results then from ML.



Consider the posterior probability  $p(c_1|y)$ 

$$p(c_1|y) = \frac{p(y|c_1)p(c_1)}{p(y|c_2)p(c_2) + p(y|c_1)p(c_1)} = \frac{1}{1 + \exp(-l)}$$

We introduced here the **Likelihood ratio** *l*:

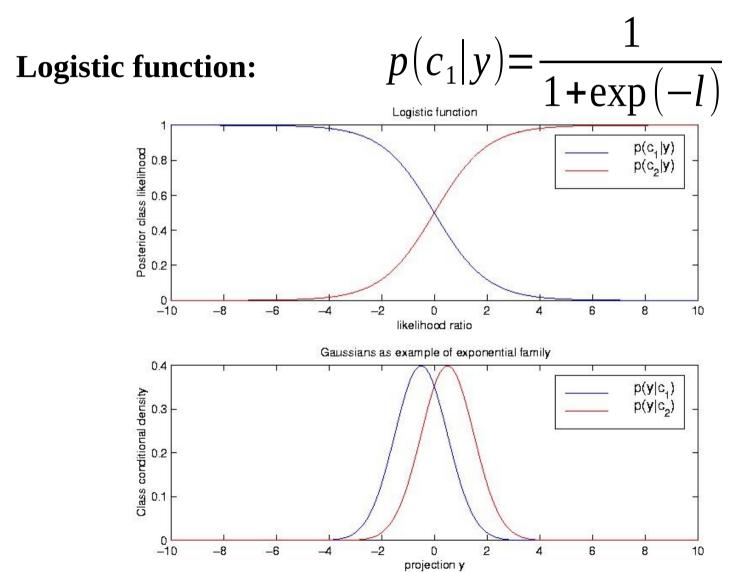
$$l = \ln \frac{p(y|c_1) p(c_1)}{p(y|c_2) p(c_2)}$$

For a large class of distributions, p(y|c), called exponential family, the Likelihood ratio simplifies under certain assumptions to

$$l = y + \ln \frac{p(c_1)}{p(c_2)}$$



For example Gaussian projections,  $p(y|c) = N(y;\mu_c,\sigma)$  with different mean for each class but the same standard deviation.





#### **Linear Discrimination - Gaussian Data**

**Example:** If the two classes are Gaussian distributed with different mean for each class but the *same covariance matrix* their optimal separation is linear and solution is particularly simple:

$$p(\mathbf{x}|\mathbf{c}) \propto \exp\left[-(\mathbf{x}-\mathbf{\mu}_{\mathbf{c}})^{T} \mathbf{\Sigma}^{-1} (\mathbf{x}-\mathbf{\mu}_{\mathbf{c}})/2\right]$$

The likelihood ration is then linear

$$l = \ln \frac{p(\mathbf{x}|c_1)p(c_1)}{p(\mathbf{x}|c_2)p(c_2)} = \mathbf{v}^T \mathbf{x} + \mathbf{v}_0$$

where the separation vector and bias are given by the means and covariance:

$$\mathbf{v} = \mathbf{\Sigma}^{-1} (\mu_1 - \mu_2)$$

$$v_0 = -\frac{1}{2} \mu_1^T \mathbf{\Sigma}^{-1} \mu_1 + \frac{1}{2} \mu_2^T \mathbf{\Sigma}^{-1} \mu_2 + \ln \frac{p(c_1)}{p(c_2)}$$



More generally, assume that *y* is distributed according to some distribution of the exponential family, which includes Gaussian, Bernoulli, Poission, and others.

The goal is then to find the optimal projection vector  $\mathbf{v}$  such that the projections,  $y = \mathbf{v}^T \mathbf{x}$ , results in a logistic likelihood for the class labels

$$p(c_1|y) = \frac{1}{1 + \exp(-\mathbf{v}^T \mathbf{x})} = f(\mathbf{v}^T \mathbf{x})$$

Here we have absorbed  $\ln p(c_1)/p(c_2)$  into  $v_0$ .



To derive the ML solution define, c=0, and, c=1, to identify the two different classes and denote in short p(c|y)=f. We can write then

$$p(c|y) = f^{c}(1-f)^{1-c}$$

This is called the Bernoulli density of *c*, and *f* is the mean:

$$\hat{c} = E[c] = f(\mathbf{v}^T \mathbf{x})$$

Note that the expected value we wanted to compute is therefore given now by the logistic function.



Given i.i.d. samples x[k], c[k] the log-likelihood of the data is

$$L(\mathbf{v}) = \ln \prod_{k} p(c[k], \mathbf{x}[k]|\mathbf{v})$$

$$= \sum_{k} \ln p(c[k]|\mathbf{v}^{T}\mathbf{x}[k]) p(\mathbf{x}[k])$$

$$= \sum_{k} c[k] \ln f(\mathbf{v}^{T}\mathbf{x}[k]) + (1 - c[k]) \ln (1 - f(\mathbf{v}^{T}\mathbf{x}[k]))$$

$$+ const.$$

And the optimum solution according to ML is

$$argmin_{\mathbf{v}} L(\mathbf{v})$$

There is not close form solution for this minimum.



However, the minimum can be computed using a fast algorithm based on Iteratively Reweighted Least Squares (IRLS). It is a type of Newton-Raphson gradient descent algorithm called Fisher Scoring method (McCullagh, Nelder 1983):

$$\mathbf{v}_{t+1} = \mathbf{v}_t - E \left[ \frac{\partial L(\mathbf{v})}{\partial \mathbf{v} \partial \mathbf{v}^T} \right]^{-1} \frac{\partial L(\mathbf{v})}{\partial \mathbf{v}}$$

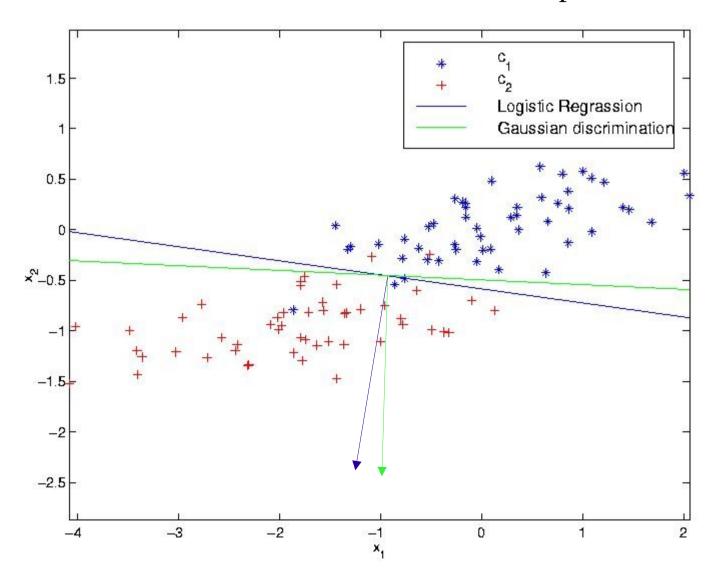
The expected Hessian can be computed fast and converges typically within a few iterations.

$$>> v = logist(x,c); % not part of matlab$$



## **Linear Discrimination - Comparison**

Gaussian solution and and minimum L(v) give different results when when data not Gaussian or for small sample size.

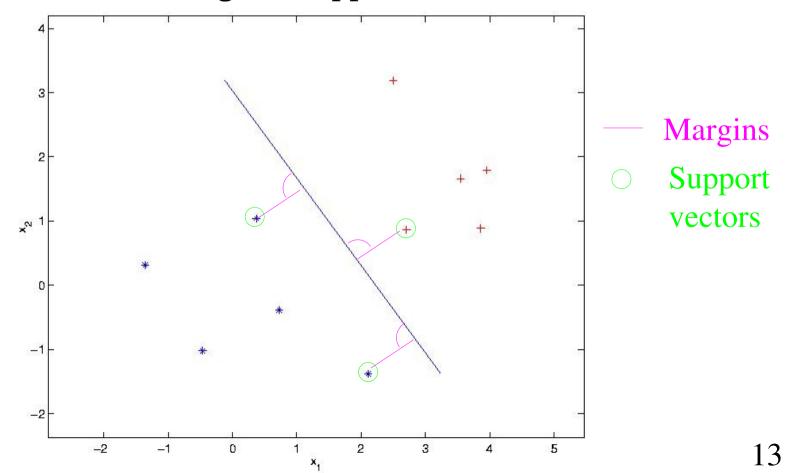




## **Linear Discrimination - Support Vectors**

In case of perfect separability LR is not well defined.

Occurs often when we have very few samples and/or high dimensions. In that case is it better to chose the separation that **maximizes the margin** to **support vectors**.

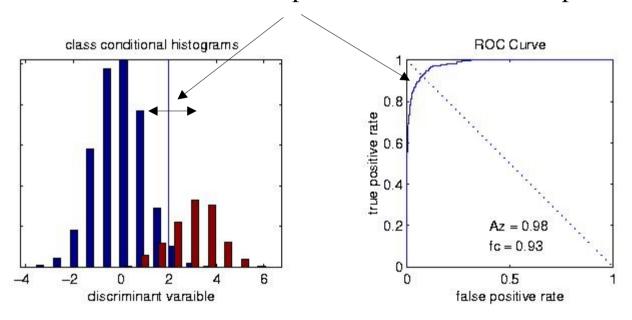




#### **Linear Discrimination - Performance**

The performance of a binary classification problem is typically evaluated with a **Receiver Operator Characteristic** (ROC) curve:

Moving threshold sweeps a curve of true positive rate versus false positive rate



**Az**: Area under the ROC curve measures performance independent of threshold. It is 0.5 for chance performance. **fc**: Fraction correct (1-error rate) is conventionally measured where tp=1-fp. It is 0.5 for chance performance.



#### **Linear Discrimination - Leave-One-Out**

Note that the performance on the training data is biased and always better than the performance on unseen data.

Therefore ROC and Az has to always be computed on unseen test data!

If there is not sufficient data available to separate into training and test set one should use the **leave-one-out procedure**:

- 1. For each sample k Find the optimal v on all data exept c[k],x[k]. Use this optimal v to compute the leave-one-out class likelihood  $p(c[k]|v^Tx[k])$ .
- 2. Compute Az using leave-one-out class likelihoods.

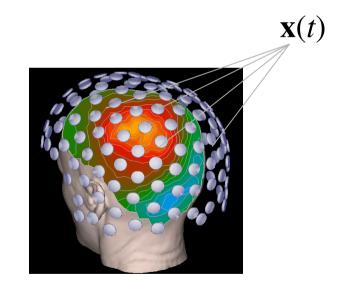


### **LD - Application to EEG and MEG**

Conventional Event Related Potentials (ERP) averages over trials to increase signal to noise ratio.

The goal is to detect single trials without averaging over trials or over time. We substitute trial averaging by spatial integration.

$$y(t)=\mathbf{v}^T\mathbf{x}(t)$$



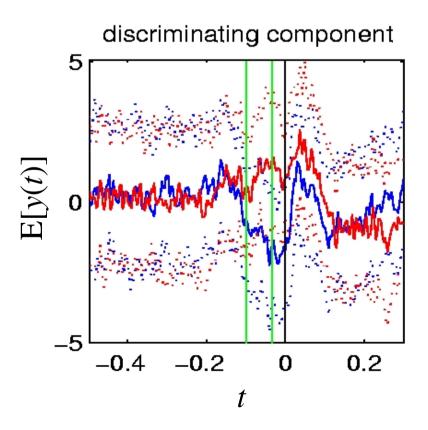
With Linear discrimination we can now compute spatial weights  $\mathbf{v}$  which maximally discriminate sensor array signals  $\mathbf{x}(t)$  for two different conditions observed at times  $t_1$  and  $t_2$ .

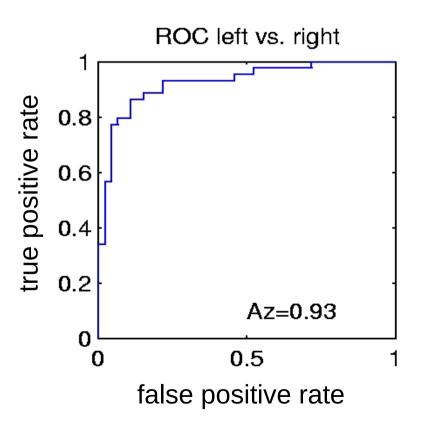


### **LD - Application to EEG and MEG**

#### Example: Find motor planing activity in MEG

Predict button press from 122 MEG sensors with linear discriminator **w** such that y(t) differs the most during 100 ms to 30 ms *prior* to left  $(t_1)$  and right  $(t_2)$  button push.







### **LD - Application to EEG and MEG**

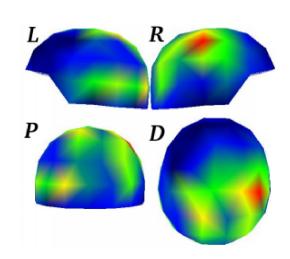
Localization of discriminating component: What is the electrical coupling a of the hypothetical source y that explains most of the activity X?

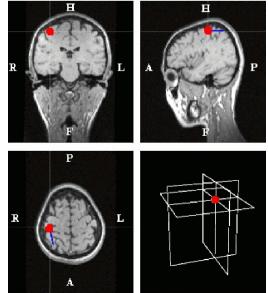
Least squares solution:

 $a = \frac{A y}{y^T y}$ 

where X has one column per sample, and y is a vector with all samples. X has to be zero mean across samples.

Strong coupling indicates low attenuation. Intensity on these "sensor projections" **a** indicates closeness of the source to the sensors.

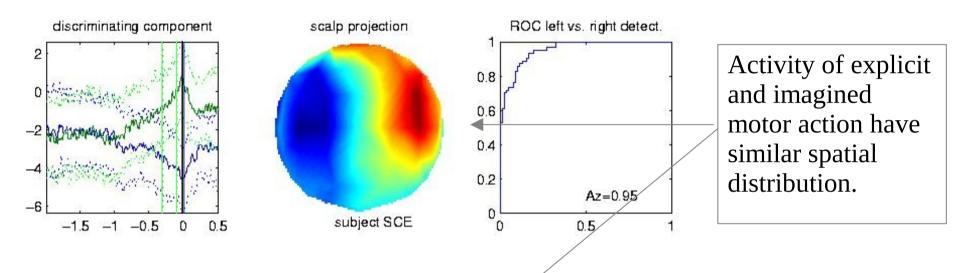




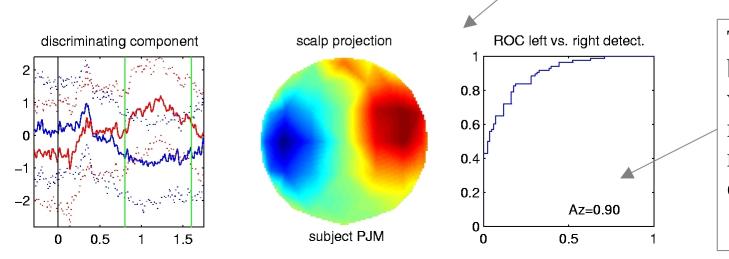


## **LD - Detection of Motor Planing and Imagery**

Prediction of explicit finger tap (59 EEG sensors, 250-100ms prior)



Detection of **imagined** finger tap (59/EEG sensors, 800 ms)



Transmission of binary information with this covert mental imagery results in communication at 12 bits/minute.



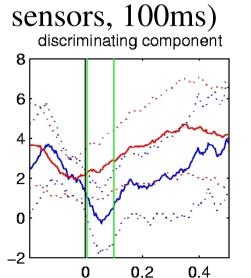
## **LD - Detection of Error Related Negativity**

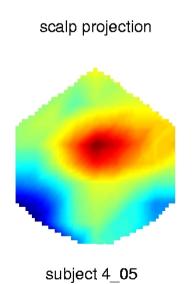
Error Related Negativity (ERN) occurs following perception of errors. It is hypothesized to originate in Anterior Cingulate and to represent response conflict or subjective loss.

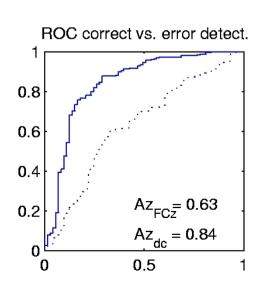
Example: Erikson Flanker task



Discrimination of error versus correct response (64 EEG



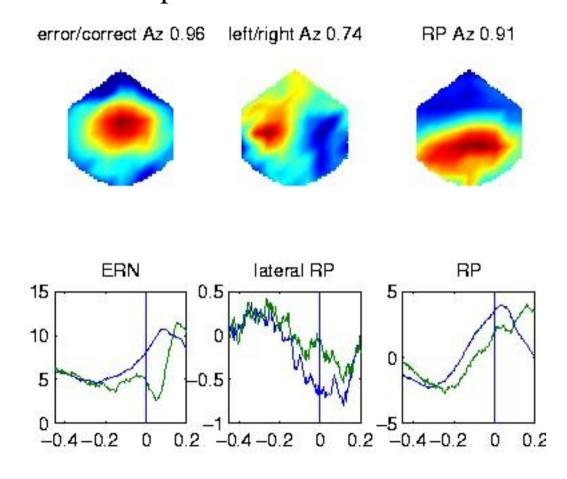






#### **LD - Detection of Readiness Potential**

In preparation of motion there is a potential buildup in the 200 ms prior to motion over motor areas. It is called readiness potential. When differentiating left/right one observed a lateralized readiness potential.





#### **LD - Detection of Readiness Potential**

#### **Assignment 11:**

Load eeg-ern.mat or generate overlapping random variables x1 and x2.

If you use eeg-ern.mat note that for every trail (78 for x1 and 300 for x2) there are each 25 samples. Consider them all as i.i.d. samples.

Find a linear discriminator that discriminates between x1 and x2 assuming Gaussian distributions.

Plot resulting v and show ROC and Az value on training data.

#### **Optional:**

Display scalp projection a using scalp (coord, a)

Show ROC curve and Az with the average y over 25 samples of each trial.

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